

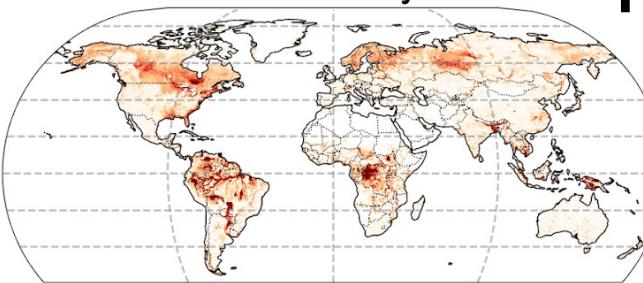
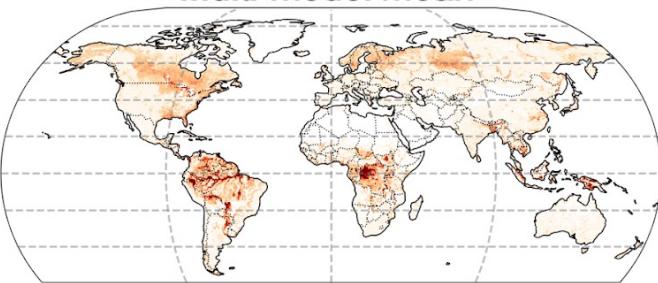
# **Recent advances in monitoring and modeling of global wetland CH<sub>4</sub> emission**

**Qing Zhu; William Riley; Kunxiaoja Yuan**

**Lawrence Berkeley National Lab, Climate Sciences  
Department, Climate & Ecosystem Sciences Division**

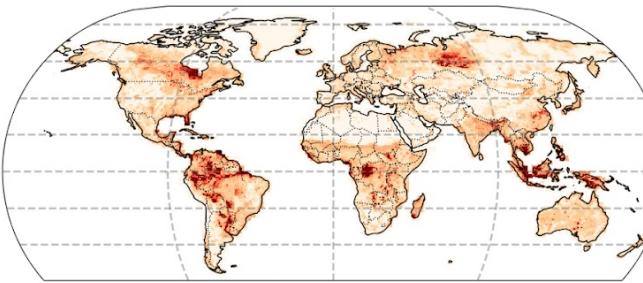
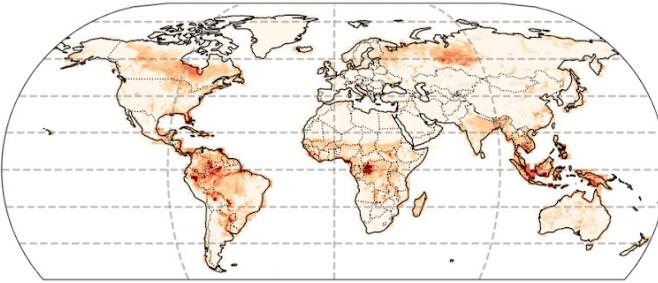
# 10 years of efforts

WETCHARTS



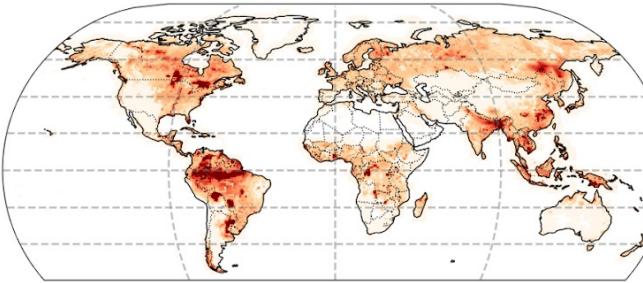
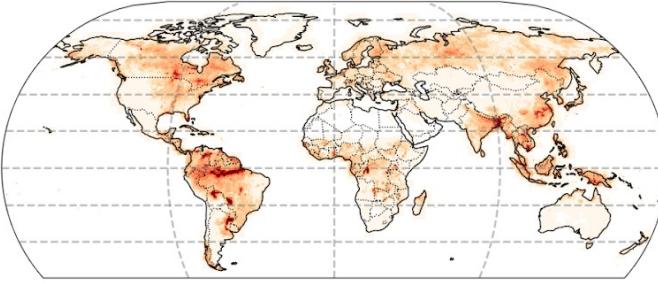
Bloom 2017  
125-208 Tg/yr

GCP



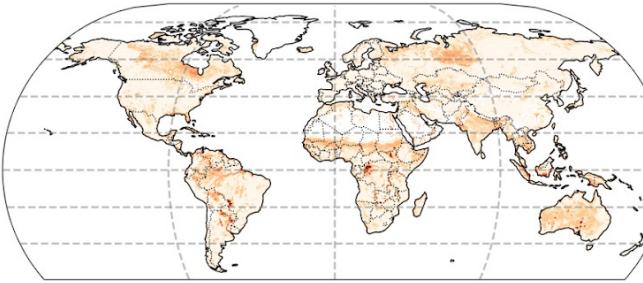
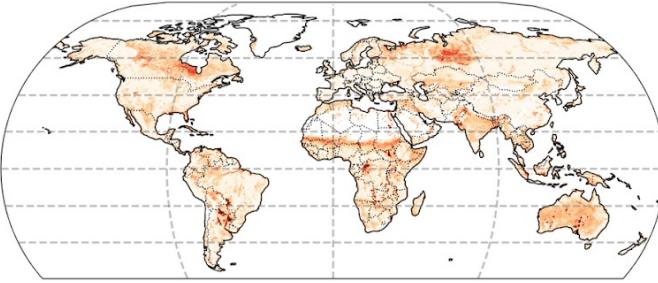
Saunois 2020  
102-182 Tg/yr

WETCHIMP

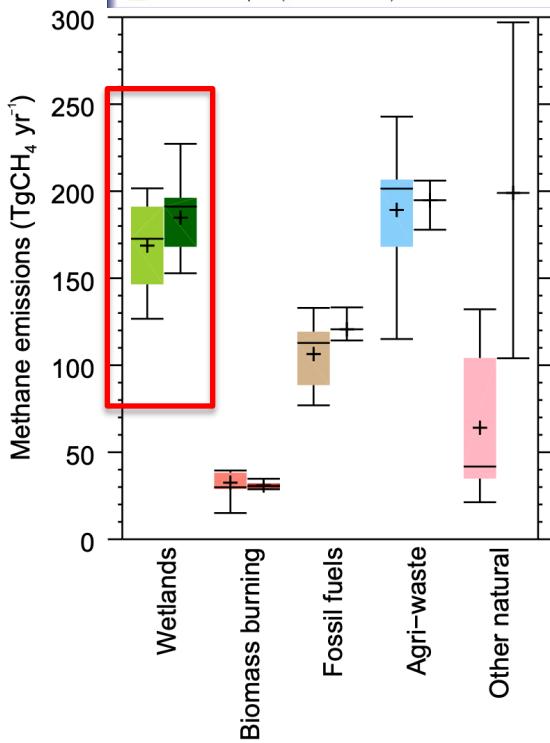
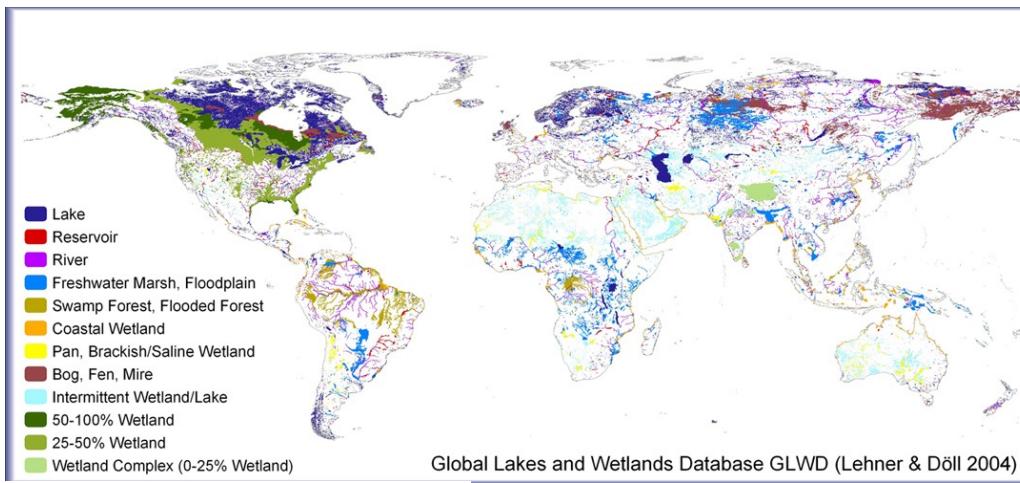


Melton 2013  
151-229 Tg/yr

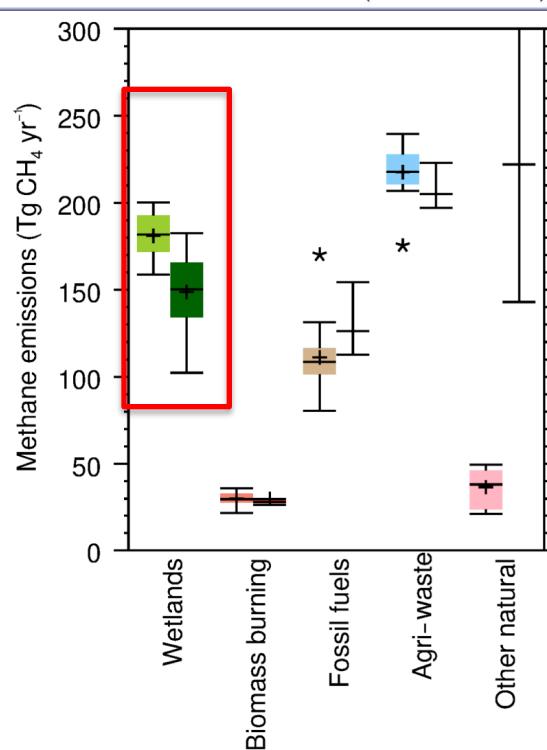
UpCH4



McNicoll 2023  
103-189 Tg/yr



GCP-CH4 (Saunois et al., 2016)

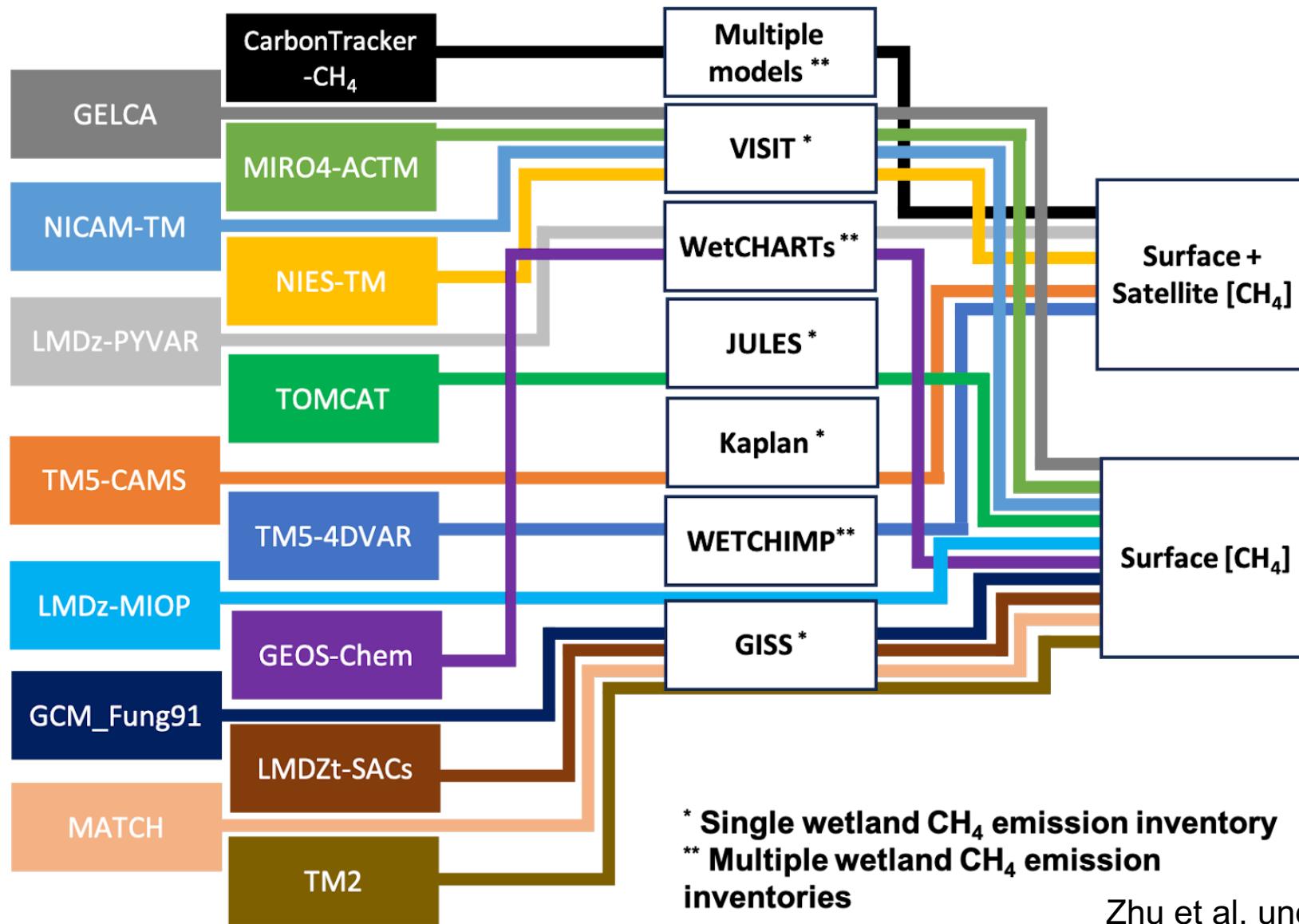


GCP-CH4 (Saunois et al., 2019)

## Top-down inversion system

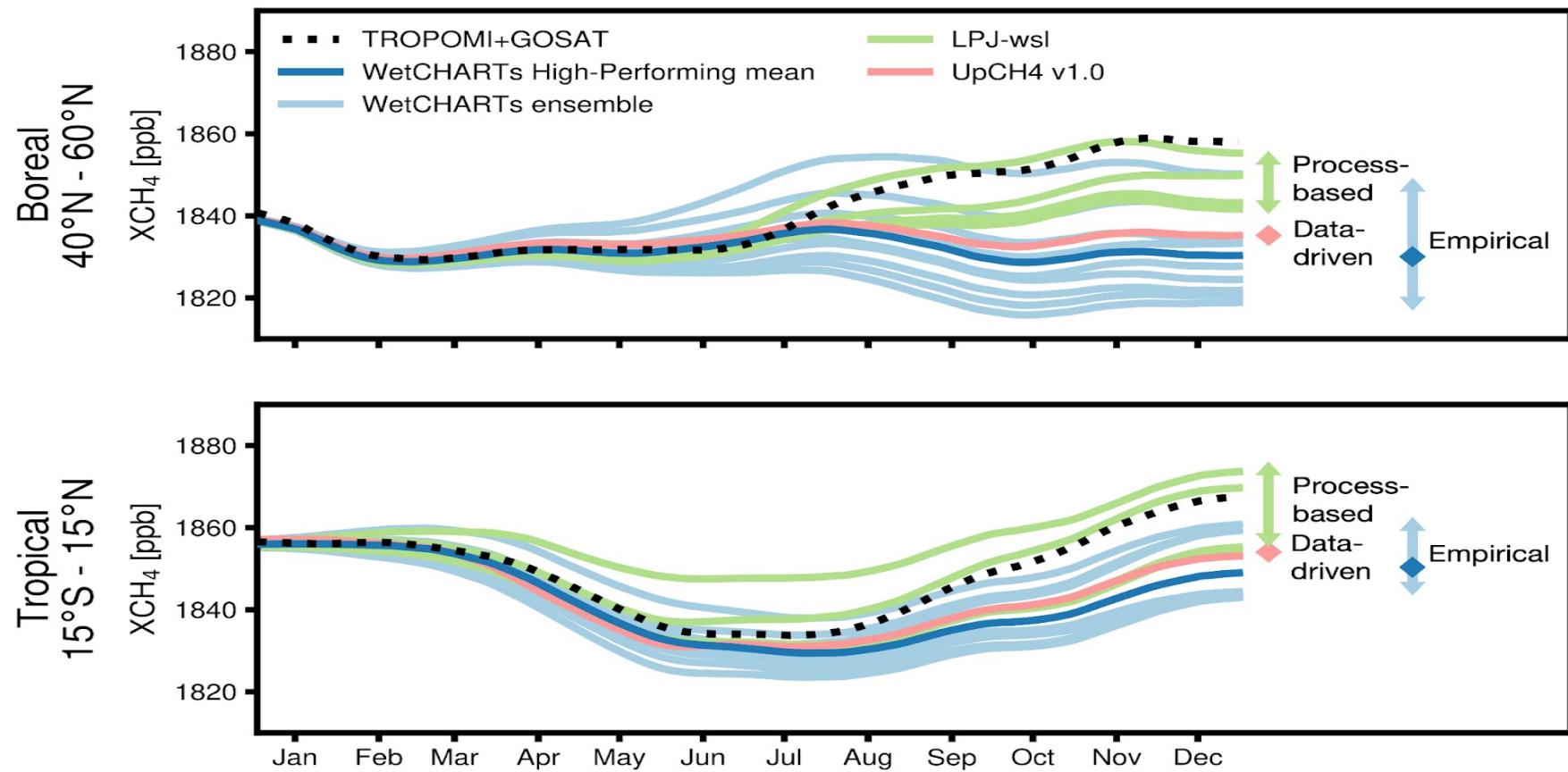
## Wetland CH<sub>4</sub> emission inventory

## Atmospheric CH<sub>4</sub> concentrations



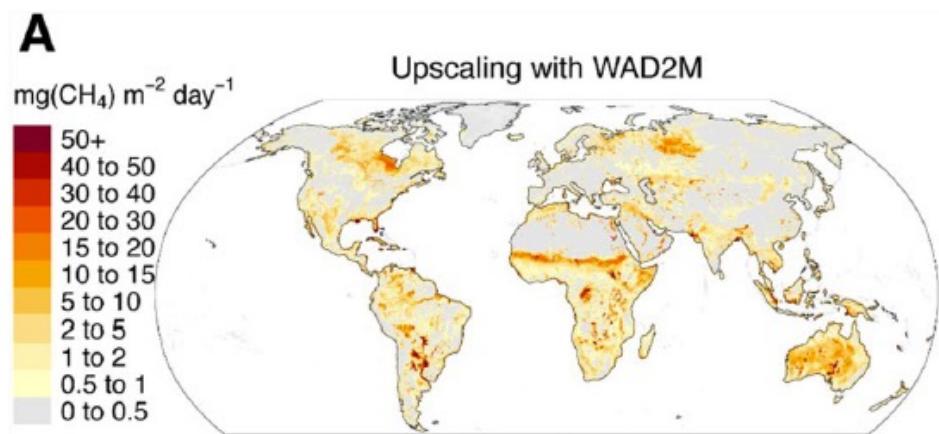
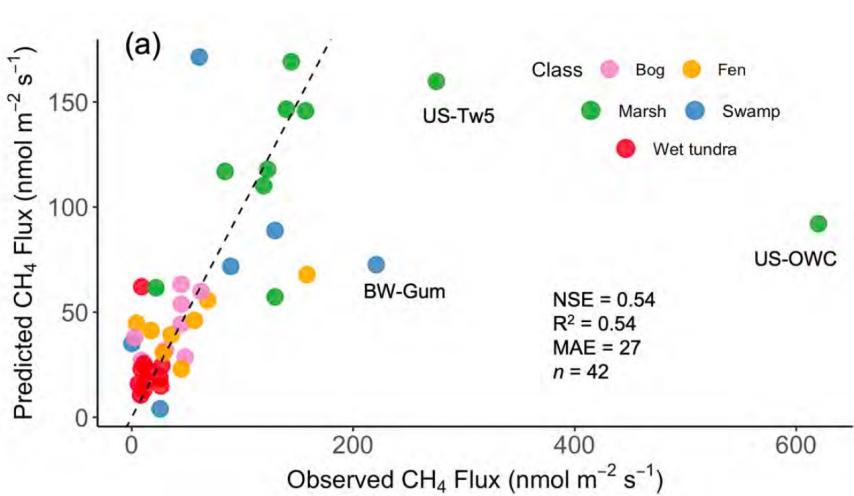
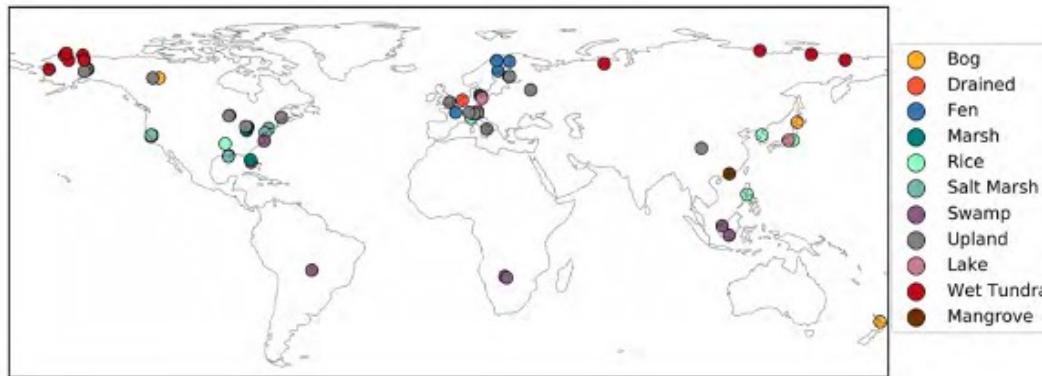
Zhu et al. under review

# Uncertainty propagation to XCH<sub>4</sub>



Zhu et al. under review

## FLUXNET-CH<sub>4</sub> Version 1.0: 81 sites, 254 site-years



McNicol et al., 2023 AGU Advances

## 1. Process-driven: Calibrate ELM-CH4

$$\frac{\partial(RC)}{\partial t} = \frac{\partial F_D}{\partial z} + P(z, t) - E(z, t) - A(z, t) - O(z, t)$$

| a) CH-Cha (PFT-13: Cool c3 grass) |      |      |      |      |      |                 |         |                             |                |              |             |                |             |             |             |                    |                            |        |      |          |                |                             |                            |                    |
|-----------------------------------|------|------|------|------|------|-----------------|---------|-----------------------------|----------------|--------------|-------------|----------------|-------------|-------------|-------------|--------------------|----------------------------|--------|------|----------|----------------|-----------------------------|----------------------------|--------------------|
|                                   | EM   | PROD | DIFF | EBUL | AERE | Q <sup>10</sup> | $\beta$ | f <sub>CH<sub>4</sub></sub> | Z <sub>r</sub> | $\tau_{cwd}$ | $\tau_{l1}$ | $\tau_{l2-l3}$ | $\tau_{s1}$ | $\tau_{s2}$ | $\tau_{s3}$ | C <sub>e,max</sub> | f <sub>D<sub>0</sub></sub> | $\rho$ | R    | $\tau_L$ | F <sub>a</sub> | K <sub>CH<sub>4</sub></sub> | K <sub>O<sub>2</sub></sub> | R <sub>o,max</sub> |
| EM                                | 0.67 | 0.03 | 0.14 | 0.02 | 0    | 0.01            | 0       | 0.00                        | 0.00           | 0            | 0           | 0              | 0           | 0           | 0           | 0                  | 0.00                       | 0.00   | 0    | 0        | 0.00           | 0.02                        |                            |                    |
| PROD                              | 0.77 | 0.01 | 0.15 | 0.02 | 0    | 0               | 0       | 0                           | 0              | 0            | 0           | 0              | 0           | 0           | 0           | 0                  | 0                          | 0.02   | 0    | 0        | 0              | 0                           | 0                          |                    |
| DIFF                              | 0.53 | 0.01 | 0.19 | 0.01 | 0    | 0.00            | 0       | 0.00                        | 0              | 0            | 0.02        | 0.11           | 0           | 0           | 0           | 0                  | 0                          | 0      | 0.02 | 0.02     | 0              | 0                           | 0                          |                    |
| EBUL                              | 0.63 | 0    | 0.26 | 0.03 | 0    | 0.00            | 0       | 0.00                        | 0              | 0            | 0.01        | 0.01           | 0           | 0           | 0           | 0                  | 0                          | 0.15   | 0.01 | 0        | 0              | 0                           | 0                          |                    |
| AERE                              | 0.17 | 0    | 0.23 | 0.01 | 0    | 0               | 0       | 0                           | 0              | 0            | 0           | 0              | 0.00        | 0.00        | 0.01        | 0                  | 0                          | 0.15   | 0.01 | 0.33     | 0              | 0                           | 0                          |                    |

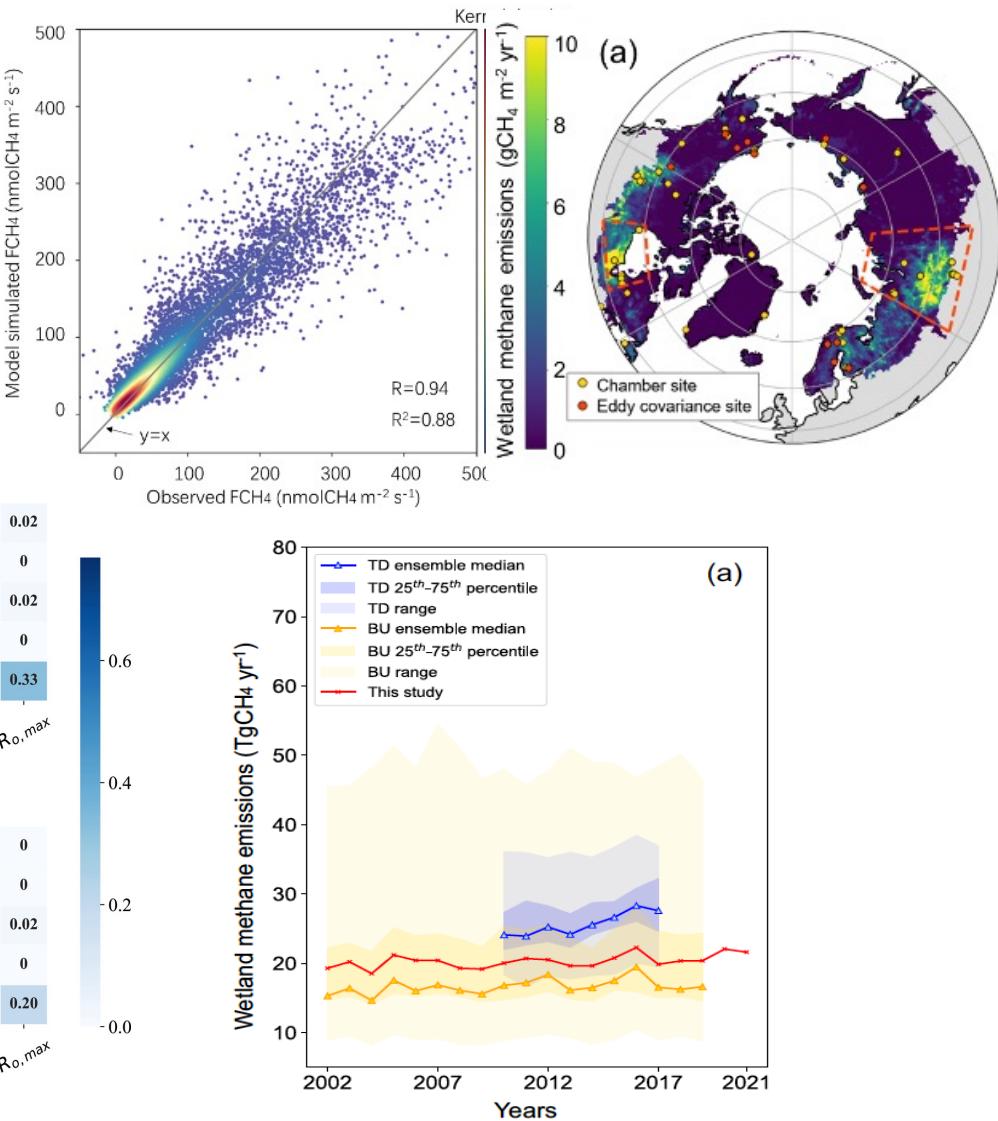
Parameters

| b) SE-Deg (PFT-12: Arctic c3 grass) |      |      |      |      |      |                 |         |                             |                |              |             |                |             |             |             |                    |                            |        |      |          |                |                             |                            |                    |
|-------------------------------------|------|------|------|------|------|-----------------|---------|-----------------------------|----------------|--------------|-------------|----------------|-------------|-------------|-------------|--------------------|----------------------------|--------|------|----------|----------------|-----------------------------|----------------------------|--------------------|
|                                     | EM   | PROD | DIFF | EBUL | AERE | Q <sup>10</sup> | $\beta$ | f <sub>CH<sub>4</sub></sub> | Z <sub>r</sub> | $\tau_{cwd}$ | $\tau_{l1}$ | $\tau_{l2-l3}$ | $\tau_{s1}$ | $\tau_{s2}$ | $\tau_{s3}$ | C <sub>e,max</sub> | f <sub>D<sub>0</sub></sub> | $\rho$ | R    | $\tau_L$ | F <sub>a</sub> | K <sub>CH<sub>4</sub></sub> | K <sub>O<sub>2</sub></sub> | R <sub>o,max</sub> |
| EM                                  | 0.74 | 0.01 | 0.15 | 0.01 | 0    | 0               | 0       | 0                           | 0              | 0            | 0           | 0              | 0           | 0           | 0           | 0                  | 0                          | 0      | 0    | 0        | 0              | 0                           | 0                          |                    |
| PROD                                | 0.77 | 0.01 | 0.15 | 0.01 | 0    | 0               | 0       | 0                           | 0              | 0            | 0           | 0              | 0.00        | 0           | 0           | 0                  | 0                          | 0      | 0    | 0        | 0              | 0                           | 0                          |                    |
| DIFF                                | 0.50 | 0    | 0.21 | 0.03 | 0    | 0.00            | 0.00    | 0.01                        | 0.00           | 0            | 0.02        | 0.13           | 0           | 0           | 0           | 0                  | 0                          | 0      | 0.01 | 0.02     | 0              | 0                           | 0                          |                    |
| EBUL                                | 0.62 | 0    | 0.24 | 0.04 | 0    | 0.00            | 0       | 0.00                        | 0.00           | 0            | 0.01        | 0.01           | 0.00        | 0           | 0           | 0                  | 0                          | 0      | 0    | 0        | 0              | 0                           | 0                          |                    |
| AERE                                | 0.26 | 0    | 0.25 | 0.06 | 0    | 0               | 0.00    | 0.00                        | 0.00           | 0.01         | 0           | 0.00           | 0           | 0           | 0           | 0                  | 0.12                       | 0.01   | 0.20 | 0        | 0              | 0                           | 0                          |                    |

Parameters

## 2. Data-driven: develop physics-guided ML



Chinta S., X. Gao, Q. Zhu 2024, JAMES

Yuan K., et al. Q. Zhu, 2024 Nature Climate Change

# Summary

- Ground measurements of CH<sub>4</sub> flux (like FLUXNET-CH<sub>4</sub>) is critical to reduce uncertainty wetland CH<sub>4</sub> emission
- Great opportunities to test different BGC formulation, calibrate physical parameters for process-based models.
- Growing opportunities to run more advanced and complex ML architectures.